The Potential of Precision Farming

Richard Godwin





Managing variability with the aid of technology and automation Harper Adams





Sources of variability:

University

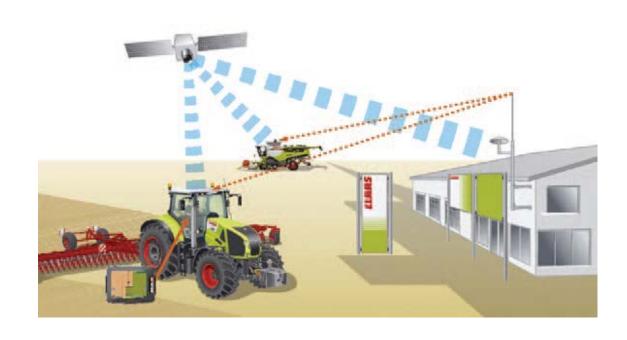
- Soil type texture
- Available water
- Soil Nutrition
- Crop Pests
- Diseases
- Weeds

Precision Farming HARVESTER GPS **Harper Adams** University GPS □±0 YIELD METER FIELDSTAR PLANT PROTECTION DATA CARD RESULT **EVALUATION** FERTILIZATION PERSONAL COMPUTER 3 EVALUATION AND DECISION ADJUSTMENT. SUPPORT YIELD MAPS OF PLANS SOIL ANALYSES **EVALUATION** SEEDING OF SOIL POTENTIAL CHOICE OF CROP PERSONAL COMPUTER CULTIVATION APPLICATION MAPS FIELDSTAR Your Agriculture Company DATA CARD *After: Moore (1995)*

Global positioning systems



GPS became "useable" in 1991 with Real Time Kinematic accurate to 2-3 cm



Auto guidance: Northern China









Random traffic farming (RTF)

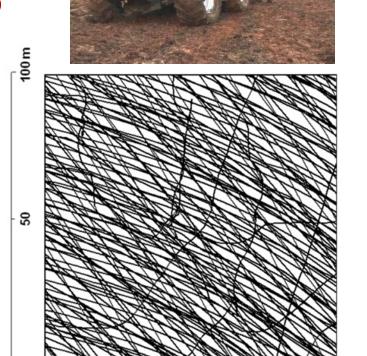


Extensive areas of the

field are exposed to

trafficking

- Plough tillage
 - = 85% covered
- Minimum Tillage
 - = 65% covered
- Direct Drilling
 - = 45% covered



50

Wheat crop

---- harvest

---- presowing soil preparation

—— straw baling

— ploughing

— straw carting

—— spraying rows

liquid manure transport

liquid manure application

---- seeding

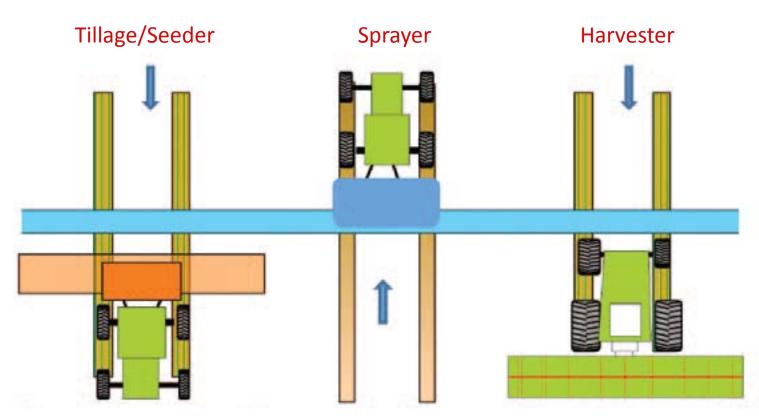
100 m

grain carting

Controlled traffic farming

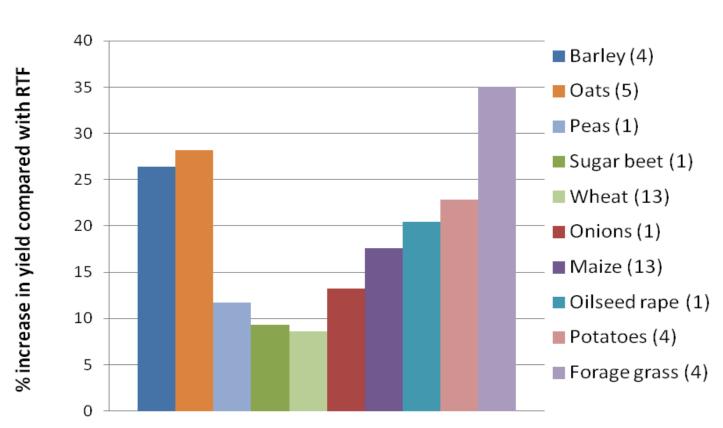






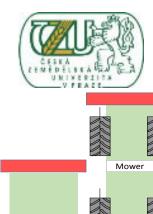
Average yield benefit from CTF





Average yield benefit from CTF compared to random traffic farming.

Numbers in parenthesis indicate the number of studies reported. Chamen, 2011

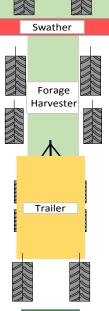


Grassland CTF



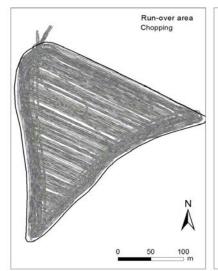






Slurry tanker







10% improvement in dry matter yield from 2nd and 3rd cut silage.

Automation and machine control



Leader – Follower tractors





Hands Free Hectare

www.handsfreehectare



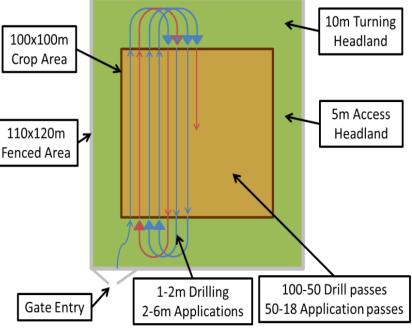
Automated machines growing the first arable crop remotely, without operators in the driving seats or agronomists on the ground.

- Commercial compact Ag machinery
- "Open source" automation
- •1 year project!!





Hands Free Hectare



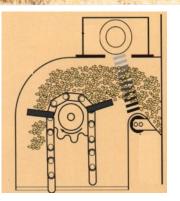


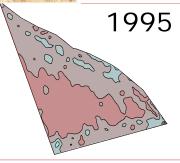


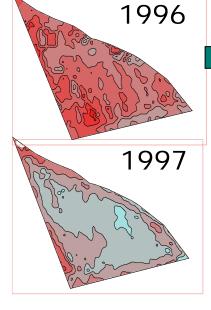
Yield maps

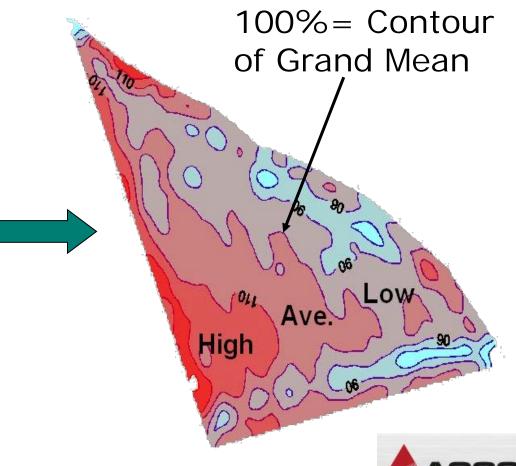


Your Agriculture Company







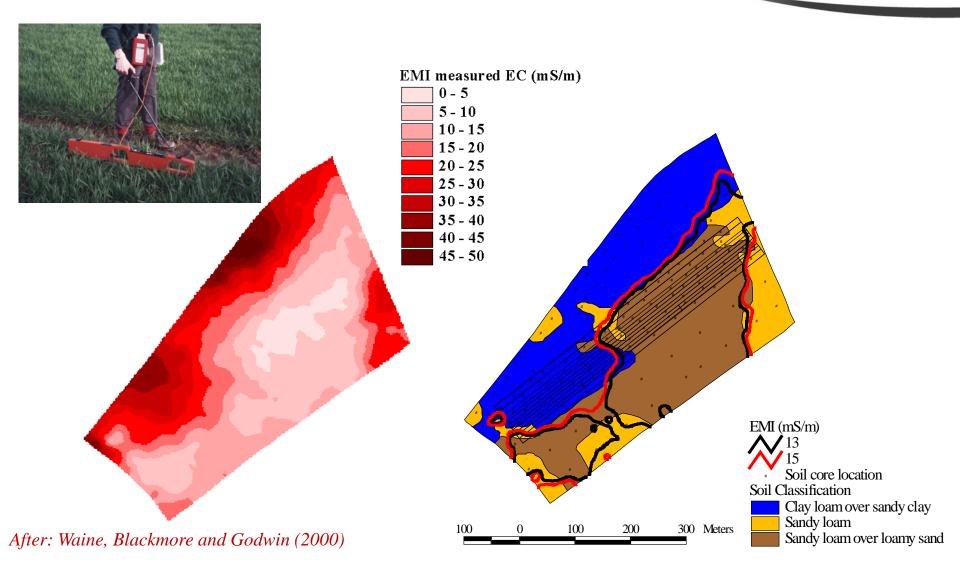




Soil uniformity

Soil electrical conductivity map, sampled on a 10 m x 24 m grid

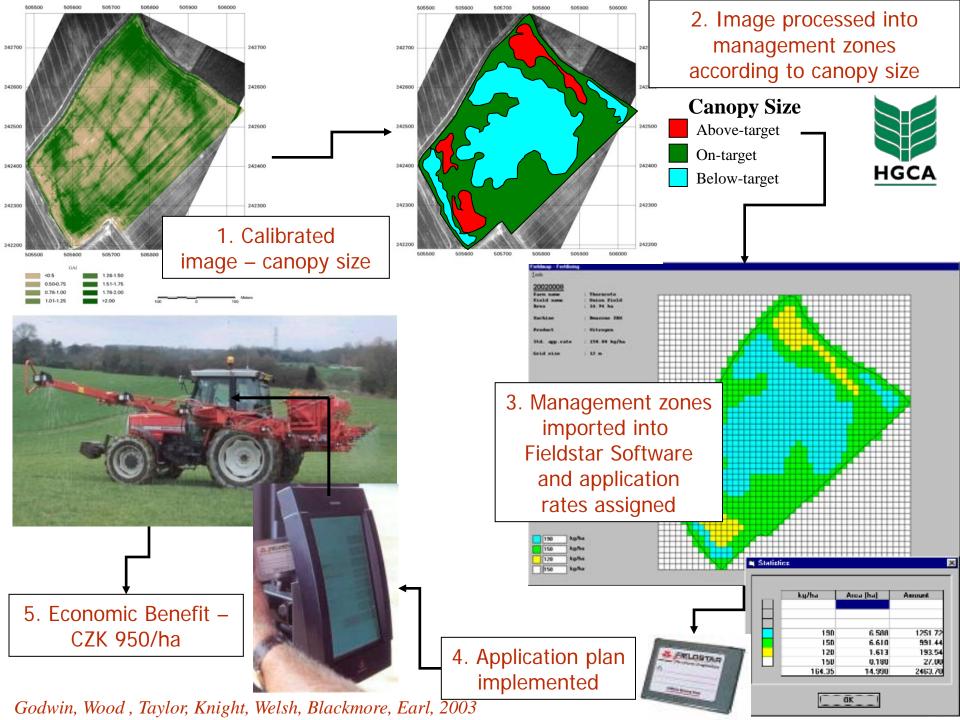




Managing spatial variability



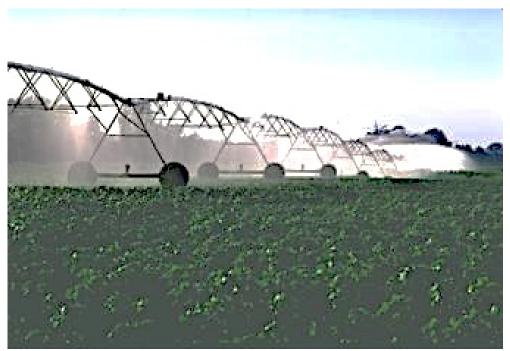




Water application rate control

Linking irrigation scheduling to soil variability











Shielded band sprayer with Auto-steer







Weed control 20 row machine in celery





Tillett and Hague Technology & Garford Engineering



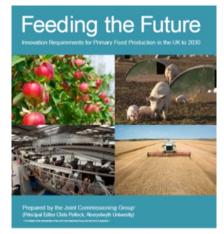
Laser Weeding



- Machine vision recognises the growing point of the weed
- Laser kills the weed by heating the growing point
- Saving 100% herbicide
- Harper Adams University is now building a real-time robot to laser and microdot weeds
- Funded by a major agrochemical company 2014-2017



Recommendations from the UK agricultural industry Harper Adams





Feeding the Future, 2013,



- 1. Use modern technologies to improve the precision and efficiency of key agricultural management practices
 - O Develop remote monitoring, control and application technologies to optimise input use efficiency, ..., sustain product quality and safety, reduce the impact of machinery traffic on land ...

University

- O Integrate and use the increasing volume of yield mapping & recording, and soil, crop and animal data, in order to develop better decision making tools...
- o Improve machine and instrument flexibility, interoperability, applicability ... to promote delivery of the above.
- Develop integrated strategic approaches to the use of nutrients and substrates to reduce environmental impact.
- 7. Extend training, professional development and communication channels of researchers, practitioners and advisors to promote delivery of the above.